

TAKEOFF2 Manual,

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TAKEOFF2.FOR is a FORTRAN implementation of a modified approach proposed by Krenkel and Salzman to solve for aircraft takeoff. The original methodology solved the aircraft equations of motion parametrically, whereas this program solves through a time-step integration technique. The methodology was also modified to calculate Balanced Field Length (BFL) for preliminary design purposes. Balanced field length is often, as here, defined as the distance required to make either a One Engine Inoperative (OEI) takeoff (including obstacle passage) or a braked stop when an engine fails at critical engine failure speed.

Krenkel and Salzman assumed thrust vectoring capability and thrust variation with velocity to create the balance of forces equations on the aircraft during its takeoff run. All necessary input parameters can be obtained from the performance parameters necessary for preliminary aircraft design. Some sources for estimating design parameters are located below.

The program is broken into two, each describing different aspects in a takeoff analysis:

- 1) Normal Takeoff - From stop to liftoff to passage over a 35ft (11m) obstacle.
- 2) Balance Field Length calculation - Iterative solution to find where the engine can fail so that the distance to perform a OEI takeoff is equal to the distance to brake to a stop.

Each section prints out important times, distances and velocities for the takeoff run. For normal takeoff, incremental time distance and velocity data is output as well.

References

Krenkel, A.R., Salzman, A., "Takeoff Performance of Jet-Propelled Conventional and Vectored Thrust STOL Aircraft", *Journal of Aircraft*, Vol. 5, No. 5, 1968, pp. 429.

Roskam, Jan, *Airplane Design Part 1: Preliminary Sizing of Airplanes*, Roskam Aviation and Engineering Corp., Ottawa, KS, 1989.

Torenbeek, Egbert, *Synthesis of Subsonic Airplane Design*, Kluwer Academic Publishers, Norwell, MA, 1982.

Input Format

The input file to the program (TAKEOFF2.IN) was designed to be self-explanatory and to provide a ready reference to some of the input parameters. The twenty five input parameters (two of which control output) are FORTRAN unformatted input, although 15 spaces have been allocated for each input. As will be noticed, each input line contains a description of the input necessary for that line. Note that all input is in english engineering units, as is the output. A sample input file is included below.

Note: File TAKEOFF1.INB is a blank version of the input file.

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TEST RUN DC9                (03/10/93) <- Run Title and Information
.002376900                 <- Density of air at takeoff (sl/ft^3)
95000.0                     <- Weight of aircraft      (lbs)
1000.                       <- Wing area of aircraft   (ft^2)
2.000                       <- CLmax - max lift coefficient of the aircraft
0.30                        <- CLgrd - lift coeff. for ground run takeoff segment
1.6500                      <- CLair - lift coeff. for climb takeoff segment
.080                         <- CDgrd - drag coeff. for ground run takeoff segment
0.121                       <- CDair - drag coeff. for climb takeoff segment
.025                         <- MUgrd - rolling friction coefficient *Note 1*
.3                            <- MUbrk - braking friction coefficient *Note 2*
0.0                          <- LAMBDA - thrust deflection angle, positive up (rad)
1.1                           <- K - stall margin *Note 3*
3.                             <- TIME between engine failure and braking (sec) *Note4*
35.                           <- OBSHT - height of obstacle (ft) (usu 35 or 50 ft)
0.5                           <- PLOSS - fraction of power remaining when engine fails
31450.0                      29835.0      28475.0      <- 3 thrusts (lbs) *Note 5*
0.                             111.6        334.          <- 3 velocities (ft/s)
1.00                          <- TSTEP - time step for incremental output (sec) *Note 6*
3.                             <- TROT  - time required for rotation
7                               <- Integer for output device *Note 7*

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Note 1: Rolling friction coefficient is typically:

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    Dry concrete/Asphalt - 0.02
    Hard turf/Gravel     - 0.04
    Short, dry grass     - 0.05
    Long grass           - 0.10
    Soft Ground          - 0.10 to 0.30

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Note 2: Braking friction coefficient is typically:

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    0.20 to 0.40 with good assumptions being, 0.30 or 0.35

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Note 3: Takeoff speed is usually defined as $V_{to} = k * V_{stall}$, where k is the stall margin and V_{stall} is the aircraft stall speed. k is usually defined as 1.1, although 1.2 is also used, (ie. the takeoff speed is 10% to 20% higher than stall speed).

Note 4: This is the time lag between engine failure and the decision to begin braking.
(by MIL-M-007700B this is 3 sec after failure)

Note 5: These three thrusts are used to calculate a quadratic thrust curve for the aircraft engine. Each thrust should correspond to the velocity below it. For cases with unknown thrust curves a constant thrust can be entered for three different velocities.

Note 6: This is the time step between incremental distance and velocity output points. From experience, 0.25, 0.5 or 1.0 second intervals work well. This time step is only for display purposes as the adaptive differential equation solver will often break the internal step size down to maintain solution integrity.

Note 7: Output destination is specified by the following integers:

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    6 - Sends output to the printer
    7 - Sends output to a file
    8 - Sends output to the screen

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Note 7: This integer number specifies how many data points will be generated for each curve. For instance, 20 as an input will create 20 points between $V=0$ and $V= V_{to}$ for normal takeoff.

