## Appendix A Geometry for Aerodynamicists

Aerodynamicists control the flowfield through geometry definition, and are always interested in possible geometric shapes that would be useful in design. This appendix provides the detailed definition of many of the classic shapes frequently specified in aerodynamics. It is not encyclopedic. Section A.1.1 gives some other sources for airfoils.

## A. 1 Airfoil Geometry

## The NACA Airfoils

The NACA airfoils were designed during the period from 1929 through 1947 under the direction of Eastman Jacobs at the NACA's Langley Field Laboratory. Most of the airfoils were based on simple geometrical descriptions of the section shape, although the 6 and 6 A series were developed using theoretical analysis and don't have simple shape definitions. Although a new generation of airfoils has emerged as a result of improved understanding of airfoil performance and the ability to design new airfoils using computer methods, the NACA airfoils are still useful in many aerodynamic design applications. A number of references have been included to allow the reader to study both the older NACA literature and the new airfoil design ideas. Taken together, this literature provides a means of obtaining a rather complete understanding of the ways in which airfoils can be shaped to obtain desired performance characteristics.

The NACA airfoils are constructed by combining a thickness envelope with a camber or mean line. The equations which describe this procedure are:

$$
\begin{align*}
& x_{u}=x-y_{t}(x) \sin \theta  \tag{A-1}\\
& y_{u}=y_{c}(x)+y_{t}(x) \cos \theta
\end{align*}
$$

and

$$
\begin{align*}
x_{l} & =x+y_{t}(x) \sin \theta  \tag{A-2}\\
y_{l} & =y_{c}(x)-y_{t}(x) \cos \theta
\end{align*}
$$

where $y_{t}(x)$ is the thickness function, $y_{C}(x)$ is the camber line function, and

$$
\begin{equation*}
\theta=\tan ^{-1}\left(\frac{d y_{c}}{d x}\right) \tag{A-3}
\end{equation*}
$$

is the camber line slope. It is not unusual to neglect the camber line slope, which simplifies the equations and makes the reverse problem of extracting the thickness envelope and mean line for a given airfoil straightforward.

The primary reference volume for all the NACA subsonic airfoil studies remains:
Abbott, I.H., and von Doenhoff, A.E., Theory of Wing Sections, Dover, 1959.
The following paragraphs provide a brief history of the development of the NACA Airfoils. Appendix B provides references to the development of the NASA advanced airfoils, which were developed from 1966- approx. 1977.

## Evolution of the NACA airfoils

1. The 4-digit foils: According to Abbott, Pinkerton found that the thickness distribution of the Clark Y and Gottingen 398 airfoils were similar, and Jacobs selected a function to describe this thickness distribution. The mean lines were selected to be described by two parabolic arcs which were tangent at the position of maximum camber.
2. The 4-digit modified foils: The camber lines were identical to the 4 -digit series, and a more general thickness distribution was defined, which allowed variations in the leading edge radius and position of maximum thickness to be investigated.
3. The 5-digit foils: The thickness distribution was kept identical to the 4-digit series, and a new camber line was defined which allowed for camber to be concentrated near the leading edge. A reflexed camber line was designed to produce zero pitching moment, but has generally not been used. These foils were derived to get good high lift with minimum $C_{m 0}$.
4. The 6-series foils: The foils were designed to maintain laminar flow over a large portion of the chord by delaying the adverse pressure gradient. The thickness envelope was obtained using exact airfoil theory, and no simple formulas are available to describe the shapes. The camber lines were designed using thin airfoil theory and simple formulas are available which describe their shape.
5. The 6A-series foils:To improve the trailing edge
structurally, the foils were designed to provide $\quad$ R-903* Loftin 1948
6. The 6A-series foils:To improve the trailing edge
structurally, the foils were designed to provide $\quad$ R-903* Loftin 1948

Primary
NACA Report Authors Date
R-460 Jacobs, Ward and Pinkerton

R-492

R-537 Jacobs, 1935
R-610 Pinkerton and 1937 Greenberg

1933

Stack and 1934 von Doenhoff

R-824* Abbott,
1945 von Doenhoff and Stivers sections with simple (nearly straight) surface geometry near the trailing edge, while maintaining the same general properties as the 6 -series foils. The camber line can be described by a simple alteration of the standard 6 -series mean line.

Historical accounts of the NACA airfoil program are contained in:
Abbott, I.H., "Airfoils," Evolution of Aircraft Wing Design, AIAA Dayton Section Symposium, March 1980, AIAA Paper 80-3033.

[^0]and
Jones, R.T., "Recollections From an Earlier Period in American Aeronautics," Annual Review of Fluid Mechanics, Vol. 9, pp. 1-11, 1977.
NASA has published two reports describing computer programs that produce the NACA airfoil ordinates:

Ladson, C.L., and Brooks, C.W., Jr., "Development of a Computer Program to Obtain Ordinates for the NACA 4-Digit, 4-Digit Modified, 5-Digit, and 16-Series Airfoils," NASA TM X-3284, November 1975.

Ladson, C.L., and Brooks, C.W., Jr., "Development of a Computer Program to Obtain Ordinates for the NACA 6- and 6A-Series Airfoils," NASA TM X-3069, September 1974. This program is included in the utility programs described in App. E, as LADSON. It is not extremely accurate for sections less than $6 \%$ thick or greater than $15 \%$ thick.
An extensive and excellent survey of the older airfoils is contained in the German book (available in English translation):

Riegels, Airfoil Sections, Butterworths, London, 1961. (English language version)
NASA supercritical airfoil development is described in the following references:
Whitcomb, "Review of NASA Supercritical Airfoils," ICAS Paper 74-10, August 1974 (ICAS stands for International Council of the Aeronautical Sciences)
Harris, C.D., "NASA Supercritical Airfoils," NASA TP 2969, March 1990.
Becker, J.V., "The High-Speed Airfoil Program," in The High Speed Frontier, NASA SP445, 1980.

## The NACA 4-Digit Airfoil

The numbering system for these airfoils is defined by:

## NACA MPXX

where $\quad \mathrm{XX}$ is the maximum thickness, $t / c$, in percent chord.
$M$ is the maximum value of the mean line in hundredths of chord,
P is the chordwise position of the maximum camber in tenths of the chord.
Note that although the numbering system implies integer values, the equations can provide 4 digit foils for arbitrary values of M, P, and XX.

An example: NACA 2412 • a $12 \%$ thick airfoil,

- a max value of the camber line of 0.02 , at $x / c=0.4$.

The NACA 4-digit thickness distribution is given by:

$$
\begin{equation*}
\frac{y_{t}}{c}=\left(\frac{t}{c}\right)\left[a_{0} \sqrt{x / c}-a_{1}(x / c)-a_{2}(x / c)^{2}+a_{3}(x / c)^{3}-a_{4}(x / c)^{4}\right] \tag{A-4}
\end{equation*}
$$

where:

$$
\begin{array}{lll}
a_{0}=1.4845 & a_{2}=1.7580 & a_{4}=0.5075 \\
a_{1}=0.6300 & a_{3}=1.4215 &
\end{array}
$$

The maximum thickness occurs at $x / c=0.30$, and the leading edge radius is

$$
\begin{equation*}
\left(\frac{r_{L E}}{c}\right)=1.1019\left(\frac{t}{c}\right)^{2} \tag{A-5}
\end{equation*}
$$

The included angle of the trailing edge is:

$$
\begin{equation*}
\delta_{T E}=2 \tan ^{-1}\left\{1.16925\left(\frac{t}{c}\right)\right\} \tag{A-6}
\end{equation*}
$$

It is important to note that the airfoil has a finite thickness at the trailing edge.
The camber line is given by:

$$
\left.\begin{array}{rl}
\frac{y_{c}}{c} & =\frac{M}{P^{2}}\left[2 P(x / c)-(x / c)^{2}\right]  \tag{A-7}\\
\frac{d y_{c}}{d x} & =\frac{2 M}{P^{2}}(P-(x / c))
\end{array}\right\} \quad\left(\frac{x}{c}\right)<P
$$

and

$$
\left.\begin{array}{rl}
\frac{y_{c}}{c} & =\frac{M}{(1-P)^{2}}\left[1-2 P+2 P(x / c)-(x / c)^{2}\right]  \tag{A-8}\\
\frac{d y_{c}}{d x} & =\frac{2 M}{(1-P)^{2}}(P-(x / c))
\end{array}\right\}\left(\frac{x}{c}\right) \geq P
$$

The camber line slope is found from (A-3) using (A-7) and (A-8), and the upper and lower surface ordinates resulting from the combination of thickness and camber are then computed using equations (A-1) and (A-2).

## The NACA 5-Digit Airfoil

This airfoil is an extension of the 4 digit series which provides additional camber lines. The numbering system for these airfoils is defined by:

## NACA LPQXX

where XX is the maximum thickness, $t / c$, in percent chord.
$\mathrm{L} \quad$ is the amount of camber; the design lift coefficient is $3 / 2 \mathrm{~L}$, in tenths
$\mathrm{P} \quad$ is the designator for the position of maximum camber, $x_{f}$, where $x_{f}=\mathrm{P} / 2$, and $P$ is given in tenths of the chord

Q $\quad=0$; standard 5 digit foil camber
= 1; "reflexed" camber

An example: NACA 23012 , is a $12 \%$ thick airfoil, the design lift coefficient is 0.3 , the position of max camber is located at $x / c=0.15$, and the "standard" 5 digit foil camber line is used.

The thickness distribution is the same as the NACA 4 digit airfoil thickness distribution described above in equation (A-4).

The standard five-digit series camber line is given by:

$$
\left.\begin{array}{rl}
\frac{y_{c}}{c} & =\frac{K_{1}}{6}\left[(x / c)^{3}-3 m(x / c)^{2}+m^{2}(3-m)(x / c)\right]  \tag{A-9}\\
\frac{d y_{c}}{d x} & =\frac{K_{1}}{6}\left[3(x / c)^{2}-6 m(x / c)+m^{2}(3-m)\right]
\end{array}\right\} \quad 0 \leq(x / c) \leq m
$$

and

$$
\left.\begin{array}{rl}
\frac{y_{c}}{c} & =\frac{K_{1}}{6} m^{3}[1-(x / c)]  \tag{A-10}\\
\frac{d y_{c}}{d x} & =-\frac{K_{1}}{6} m^{3}
\end{array}\right\} m<(x / c) \leq 1
$$

where $m$ is not the position of maximum camber, but is related to the maximum camber position by:

$$
\begin{equation*}
x_{f}=m\left(1-\sqrt{\frac{m}{3}}\right) \tag{A-11}
\end{equation*}
$$

and $m$ is found from a simple fixed point iteration for a given $x_{f} K_{1}$ is defined to avoid the leading edge singularity for a prescribed $C_{l i}$ and $m$ :

$$
\begin{equation*}
K_{1}=\frac{6 C_{l_{i}}}{Q} \tag{A-12}
\end{equation*}
$$

where:

$$
\begin{equation*}
Q=\frac{3 m-7 m^{2}+8 m^{3}-4 m^{4}}{\sqrt{m(1-m)}}-\frac{3}{2}(1-2 m)\left[\frac{\pi}{2}-\sin ^{-1}(1-2 m)\right] \tag{A-13}
\end{equation*}
$$

Note that $K_{1}$ is a linear function of $C_{l i}$ and the $K_{1}$ 's were originally tabulated for $\mathrm{C}_{l i}=.3$. The tabulated $K_{1}$ 's are multiplied by $\left(C_{l i} / 3\right)$ to get values at other $C_{l i}$. To compute the camber line, the values of Q and K 1 must be determined. In some cases the computed values of $K_{1}$ and $Q$ differ slightly from the official tabulated values (remember these were computed in the 1930s). The tabulated values should be used to reproduce the official ordinates. The following table illustrates the differences.

| Mean Line | m |  |  | tabulated | using tabulated $m$ | using computed $m$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\underline{x}_{f}$ | tabulated | computed |  |  |  |
| 210 | 0.05 | 0.0580 | 0.0581 | 361.4 | 351.56 | 350.332 |
| 220 | 0.10 | 0.1260 | 0.1257 | 51.65 | 51.318 | 51.578 |
| 230 | 0.15 | 0.2025 | 0.2027 | 15.65 | 15.955 | 15.920 |
| 240 | 0.20 | 0.2900 | 0.2903 | 6.643 | 6.641 | 6.624 |
| 250 | 0.25 | 0.3910 | 0.3913 | 3.230 | 3.230 | 3.223 |

Once the camberline parameters are chosen, the airfoil is constructed using the equations given above.

Camber lines designed to produce zero pitching moment.

The reflexed mean line equations were derived to produce zero pitching moment about the quarter chord.

$$
\begin{array}{rlr}
\frac{y_{c}}{c}= & \frac{K_{1}}{6}\left[\{(x / c)-m\}^{3}-\frac{K_{2}}{K_{1}}(1-m)^{3}(x / c)-m^{3}(x / c)+m^{3}\right] & 0 \leq(x / c) \leq m \\
& =\frac{K_{1}}{6}\left[\frac{K_{2}}{K_{1}}\{(x / c)-m\}^{3}-\frac{K_{2}}{K_{1}}(1-m)^{3}(x / c)-m^{3}(x / c)+m^{3}\right] & m<(x / c) \leq 1 \tag{A-15}
\end{array}
$$

where

$$
\begin{equation*}
\frac{K_{2}}{K_{1}}=\frac{3\left(m-x_{f}\right)^{2}-m^{3}}{(1-m)^{3}} \tag{A-16}
\end{equation*}
$$

The parameters are defined as follows: i) given $x_{f}$, find $m$ to give $C_{m \mathrm{c} / 4}=0$ from thin airfoil theory; ii) given $x_{f}$ and $m$, calculate $K_{1}$ to give $C_{l i}=0.3$.

The tabulated values for these camber lines are:

| Mean | $(\mathrm{P} / 2)$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Line | $\underline{x_{f}}$ | $\underline{m}$ | $\underline{K_{1}}$ | $\underline{K_{1}} \underline{1} \underline{K}_{\underline{2}}$ |
| 211 | .05 | - | - | - |
| 221 | .10 | 0.1300 | 51.99 | 0.000764 |
| 231 | .15 | 0.2170 | 15.793 | 0.006770 |
| 241 | .20 | 0.3180 | 6.520 | 0.030300 |
| 251 | .25 | 0.4410 | 3.191 | 0.135500 |

## The NACA Modified 4-Digit Airfoil

This airfoil is an extension of the 4-digit series to allow for a variation of leading edge radius and location of maximum thickness. The numbering system is defined by:

## NACA MPXX-IT

where MPXX is the standard 4-digit designation and the IT appended at the end describes the modification to the thickness distribution. They are defined as:

I - designation of the leading edge radius T - chordwise position of maximum thickness in tenths of chord

$$
\begin{equation*}
\frac{r_{l e}}{c}=1.1019\left(\frac{I}{6} \cdot \frac{t}{c}\right)^{2} \quad \text { for } I \leq 8 \tag{A-17}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{r_{e}}{c}=3 \times 1.1019\left(\frac{t}{c}\right)^{2} \quad \text { for } I=9 \tag{A-18}
\end{equation*}
$$

$\mathrm{I}=6$ produces the leading edge radius of the standard 4-digit airfoils.
An example: NACA 0012-74 denotes an uncambered $12 \%$ thick airfoil, with a maximum thickness at $x / c=0.40$ and a leading edge radius of 0.0216 , which is $36 \%$ larger than the standard 4-digit value.

The NACA 16 series is a special case of the modified 4-digit airfoil with a leading edge radius index of $\mathrm{I}=4$ and the maximum thickness located at $\mathrm{x} / \mathrm{c}=0.5(\mathrm{~T}=5)$. As an example, the NACA 16-012 is equivalent to an NACA 0012-45.

The thickness distribution is given by:

$$
\begin{equation*}
\frac{y_{t}}{c}=5\left(\frac{t}{c}\right)\left[a_{0} \sqrt{\frac{x}{c}}+a_{1}\left(\frac{x}{c}\right)+a_{2}\left(\frac{x}{c}\right)^{2}+a_{3}\left(\frac{x}{c}\right)^{3}\right] \quad 0<\frac{x}{c}<T \tag{A-19}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{y_{t}}{c}=5\left(\frac{t}{c}\right)\left[.002+d_{1}\left(1-\frac{x}{c}\right)+d_{2}\left(1-\frac{x}{c}\right)^{2}+d_{3}\left(1-\frac{x}{c}\right)^{3}\right] \quad T<\frac{x}{c} \leq 1 \tag{A-20}
\end{equation*}
$$

The coefficients are determined by solving for the $d$ 's first, based on the trailing edge slope and the condition of maximum thickness at $x / c=\mathrm{T}$. Once these coefficients are found, the $a$ 's are found by relating $a_{0}$ to the specified leading edge radius, the maximum thickness at $x / c=\mathrm{T}$, and the condition of continuity of curvature at $x / c=\mathrm{T}$. These constants are all determined for $t / c=$ 0.2 , and then scaled to other $t / c$ values by multiplying by $5(\mathrm{t} / \mathrm{c})$. The value of $d_{l}$ controls the trailing edge slope and was originally selected to avoid reversals of curvature. In addition to the tabulated values, Riegels has provided an interpolation formula.
The official (tabulated) and Riegels approximate values of $d_{1}$ are given in the following table.

| $\underline{\mathrm{T}}$ | $\underline{\text { Tabulated } d} \boldsymbol{1}$ | Approximate $d_{\mathbf{1}}$ |
| :--- | :---: | :---: |
| 0.2 | 0.200 | 0.200 |
| 0.3 | 0.234 | 0.234 |
| 0.4 | 0.315 | 0.314 |
| 0.5 | 0.465 | 0.464 |
| 0.6 | 0.700 | 0.722 |

where the Riegels approximation is given by:

$$
\begin{equation*}
d_{1} \cong \frac{\left(2.24-5.42 T+12.3 T^{2}\right)}{10(1-0.878 T)} \tag{A-21}
\end{equation*}
$$

Once the value of $d_{1}$ is known, $d_{2}$ and $d_{3}$ are found from the relations given by Riegels:

$$
\begin{equation*}
d_{2}=\frac{0.294-2(1-T) d_{1}}{(1-T)^{2}} \tag{A-22}
\end{equation*}
$$

and

$$
\begin{equation*}
d_{3}=\frac{-0.196+(1-T) d_{1}}{(1-T)^{3}} \tag{A-23}
\end{equation*}
$$

With the $d$ 's determined, the $a$ 's can be found. $a_{0}$ is based on the leading edge radius:

$$
\begin{equation*}
a_{0}=0.296904 \cdot \chi_{L E} \tag{A-24}
\end{equation*}
$$

where

$$
\begin{align*}
\chi_{L E} & =\frac{I}{6} & & \text { for } I \leq 8  \tag{A-25}\\
& =10.3933 & & \text { for } I=9
\end{align*}
$$

Defining:

$$
\begin{equation*}
\rho_{1}=\left(\frac{1}{5}\right) \frac{(1-T)^{2}}{\left[0.588-2 d_{1}(1-T)\right]} \tag{A-26}
\end{equation*}
$$

the rest of the $a$ 's can be found from:

$$
\begin{align*}
& a_{1}=\frac{0.3}{T}-\frac{15}{8} \cdot \frac{a_{0}}{\sqrt{T}}-\frac{T}{10 \rho_{1}}  \tag{A-27}\\
& a_{2}=-\frac{0.3}{T^{2}}+\frac{5}{4} \cdot \frac{a_{0}}{T^{3 / 2}}+\frac{1}{5 \rho_{1}}  \tag{A-28}\\
& a_{3}=\frac{0.1}{T^{3}}-\frac{0.375 a_{0}}{T^{5 / 2}}-\frac{1}{10 \rho_{1} T} \tag{A-29}
\end{align*}
$$

The camber lines are identical to the standard 4-digit airfoils described previously. The upper and lower ordinates are then computed using the standard equations.

## The NACA 6 and 6A-Series Mean Lines*

The 6 -series mean lines were designed using thin airfoil theory to produce a constant loading from the leading edge back to $x / c=a$, after which the loading decreases linearly to zero at the trailing edge. Theoretically, the loading at the leading edge must be either zero or infinite within the context of thin airfoil theory analysis. The violation of the theory by the assumed finite leading edge loading is reflected by the presence of a weak singularity in the mean line at the leading edge, where the camber line has an infinite slope. Therefore, according to Abbott and von Doenhoff, the 6 -series airfoils were constructed by holding the slope of the mean line constant in front of $x / c=0.005$, with the value at that point. For round leading edges the camberline values are essentially not used at points ahead of the origin of the leading edge radius. The theory is discussed by Abbott and von Doenhoff on pages 73-75, 113, and 120. Tabulated values are contained on pages 394-405. The derivation of this mean line is a good exercise in thin airfoil theory.

By simply adding various mean lines together, other load distributions can be constructed.
From Abbott and von Doenhoff: "The NACA 6-series wing sections are usually designated by a six-digit number together with a statement showing the type of mean line used. For example, in the designation NACA 65,3-218, $a=0.5$, the 6 is the series designation. The 5 denotes the chordwise position of minimum pressure in tenths of the chord behind the leading edge for the basic symmetrical section at zero lift. The 3 following the comma (sometimes this is a subscript or in parenthesis) gives the range of lift coefficient in tenths above and below the design lift coefficient in which favorable pressure gradients exist on both surfaces. The 2 following the dash gives the design lift coefficient in tenths. The last two digits indicate the thickness of the wing section in percent chord. The designation $a=0.5$ shows the type of mean line used. When the mean-line is not given, it is understood that the uniform-load mean line ( $a=$ 1.0) has been used."

The 6A series airfoils employed an empirical modification of the $a=0.8$ camberline to allow the airfoil to be constructed of nearly straight line segments near the trailing edge. This camberline is described by Loftin in NACA R-903.

## Basic Camberline Equations

When $a=1$ (uniform loading along the entire chord):

$$
\begin{equation*}
\frac{y}{c}=-\frac{C_{l_{i}}}{4 \pi}\left[\left(1-\frac{x}{c}\right) \ln \left(1-\frac{x}{c}\right)+\frac{x}{c} \ln \left(\frac{x}{c}\right)\right] \tag{A-30}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d y}{d x}=\frac{C_{l_{i}}}{4 \pi}\left[\ln \left(1-\frac{x}{c}\right)-\ln \left(\frac{x}{c}\right)\right] \tag{A-31}
\end{equation*}
$$

[^1]where $\mathrm{C}_{l i}$ is the "ideal" or design lift coefficient, which occurs at zero angle-of-attack. For $a<1$,
\[

\frac{y}{c}=\frac{C_{l_{i}}}{2 \pi(1+a)}\left\{$$
\begin{array}{c}
\frac{1}{1-a}\left[\begin{array}{c}
\frac{1}{2}\left(a-\frac{x}{c}\right)^{2} \ln \left|a-\frac{x}{c}\right|-\frac{1}{2}\left(1-\frac{x}{c}\right)^{2} \ln \left(1-\frac{x}{c}\right) \\
+\frac{1}{4}\left(1-\frac{x}{c}\right)^{2}-\frac{1}{4}\left(a-\frac{x}{c}\right)^{2}
\end{array}\right]  \tag{A-32}\\
-\frac{x}{c} \ln \left(\frac{x}{c}\right)+g-h \frac{x}{c}
\end{array}
$$\right\}
\]

with

$$
\begin{gather*}
g=\frac{-1}{(1-a)}\left[a^{2}\left(\frac{1}{2} \ln a-\frac{1}{4}\right)+\frac{1}{4}\right]  \tag{A-33}\\
h=(1-a)\left[\frac{1}{2} \ln (1-a)-\frac{1}{4}\right]+g \tag{A-34}
\end{gather*}
$$

and

$$
\begin{equation*}
\frac{d y}{d x}=\frac{C_{l_{i}}}{2 \pi(1+a)}\left\{\frac{1}{1-a}\left[\left(1-\frac{x}{c}\right) \ln \left(1-\frac{x}{c}\right)-\left(a-\frac{x}{c}\right) \ln \left(a-\frac{x}{c}\right)\right]-\ln \left(\frac{x}{c}\right)-1-h\right\} \tag{A-35}
\end{equation*}
$$

The associated angle-of-attack is:

$$
\begin{equation*}
\alpha_{i}=\frac{C_{l_{i}} h}{2 \pi(1+a)} \tag{A-36}
\end{equation*}
$$

## $a=.8$ (modified), the $6 A$-series mean line

For $0<x / c<.87437$, use the basic $a=.8$ camberline, but with a modified value of the ideal lift coefficient, $\mathrm{C}_{l i \bmod }=\mathrm{C}_{l i} / 1.0209$. For $.87437<x / c<1$, use the linear equation:

$$
\begin{equation*}
\frac{y_{c} / c}{C_{l_{i}}}=0.0302164-0.245209\left(\frac{x}{c}-0.87437\right) \tag{A-37}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d y}{d x}=-0.245209 C_{l} \tag{A-38}
\end{equation*}
$$

Note that at $x / c=1$, the foregoing approximate relation gives $y / c=-0.000589$, indicating an $\alpha$ shift of $.034^{\circ}$ for $\mathrm{C}_{l i}=1$.

## Other airfoil definition procedures

Interest in defining airfoils by a small number of parameters for use in numerical optimization has led to several recent proposed parametric representations that might be useful. In particular, the work by August and co-workers at McDonnell Douglas in St. Louis, MO, uses Chebyshev functions to obtain functions with can represent very general airfoil shapes with from 5 to 20 coefficients required. This work is described in AIAA Papers 93-0099 and 93-0100, "An Efficient Approach to Optimal Aerodynamic Design," Parts 1 and 2.

Another approach using Bezier methods frequently used in CAD surface representation software has been used by Ventkataraman. This approach uses 14 design variables to represent the airfoil, and is described in AIAA Paper 95-1875, "A New Procedure for Airfoil Definition," and AIAA Paper 95-1876, "Optimum Airfoil Design in Viscous Flows." Smith and co-workers at NASA Langley have used a similar approach based on non-uniform rational B-splines (NURBS). A description of their approach appears in AIAA Paper 93-0195, "Grid and Design Variables Sensitivity Analysis for NACA Four-Digit Wing-Sections."

## A.1.1. Tabulated Airfoil Definition and the Airfoil Library

Most modern airfoils are not described by equations, but are defined by a table of coordinates. Frequently, these coordinates are the results of a computational aerodynamic design program, and simple algebraic formulas can not be used to define the shape (this was the case with the NACA 6 -series airfoils described above). The following table provides a list of the tabulated airfoils currently available on the class disk.. The subsequent tables provide a guide to these airfoils. A standard 2F10 format (the Jameson input format) is used with each set of coordinates, in the form used as input in PANELv2. See App. D. 2 for an exact description.

Airfoil Library Disk Files:
file name comments
NACA 4 digit airfoils

| NACA 0010 | N0010.DAT |
| :--- | :--- |
| NACA 0010-35 | N001035.DAT |
| NACA 0012 | N0012.DAT |
| NACA 4412 | N44122.DAT |

NACA 6 \& 6 A airfoils
NACA 63(2)-215
N632215.DAT
NACA 63(2)-215 mod B
NACA 64A010
NACA 64A410
NACA 64(3)-418
NACA 65(1)-012
NACA 65(1)-213
NACA 65(1)A012

NACA 65(2)-215
NACA 66(3)-018
NASA General Aviation Series

LS(1)-0417
LS(1)-0417 mod
LS(1)-0413
LS(1)-0013
NASA Medium Speed Series

| MS(1)-0313 | MS10313.DAT |
| :--- | :--- |
| MS(1)-0317 | MS10317.DAT |

NASA Laminar Flow Series
NLF(1)-1215F
NLF(1)-0414F
NLF(1)-0416
NLF (1)-0414Fmod
NLF(2)-0415
HSNLF(1)-0213
HSNLF(1)-0213mod

GAW1.DAT
LS10417M.DAT
GAW2.DAT
LS10013.DAT

MS10317.DAT

NL11215F.DAT
NL10414F.DAT
NL10416.DAT
NL0414FD.DAT
NL20415.DAT
HSN0213.DAT
HSN0213D.DAT drooped le
drooped le
originally known as: $\operatorname{GA}(\mathrm{W})-1$
originally known as: $\mathrm{GA}(\mathrm{W})-2$

## NASA Supercrtical Airfoils

```
SC(2)-0402
SC(2)-0403
SC(2)-0503
SC(2)-0404
SC(2)-0406
SC(2)-0606
SC(2)-0706
SC(2)-1006
SC(2)-0010
SC(2)-0410
SC(2)-0610
SC(2)-0710
SC(2)-1010
SC(2)-0012
SC(2)-0412
SC(2)-0612
SC(2)-0712
SC(3)-0712(B)
SC(2)-0414
SC(2)-0614
SC(2)-0714
SC(2)-0518
FOIL31
SUPER11
SUPER14
```

NYU Airfoils
82-06-09
79-03-12
72-06-16
71-08-14
70-10-13
65-14-08
65-15-10
75-06-12
75-07-15

SC20402.DAT
SC20403.DAT
SC20503.DAT
SC20404.DAT
SC20406.DAT
SC20606.DAT
SC20706.DAT
SC21006.DAT
SC20010.DAT
SC20410.DAT
SC20610.DAT
SC20710.DAT
SC21010.DAT
SC20012.DAT
SC20412.DAT
SC20612.DAT
SC20712.DAT
SC20712B.DAT
SC20414.DAT
SC20614.DAT
SC20714.DAT Raymer, Ref. NASA TP 2890
SC20518.DAT
FOIL31.DAT
SUPER11.dat
SUPER14.dat

K820609.DAT
K790312.DAT
K720616.DAT
K710814.DAT
K701013.DAT
K651408.DAT
K651510.DAT
KORN.DAT the "Korn" Airfoil
K750715.DAT

Miscellaneous Transonic Airfoils

CAST 7
DSMA 523
NLR HT 731081
ONERA M6
RAE 2822
WILBY A
WILBY B
WILBY C
WILBY R
SUPER10

CAST7.DAT
DSMA523.DAT
NLRHT73.DAT
ONERAM6.DAT
RAE2822.DAT
WILBYA.DAT
WILBYB.DAT
WILBYC.DAT
WILBYR.DAT
NASA10SC.DAT
MBB-A3.DAT
also known as Foil 33
$11 \%$ thick, from ICAS paper
$14 \%$ thick, NASA TM X-72712
from AIAA Papre 75-880
from AGARD AR-138

AGARD AR-138
AGARD AR-138

## Eppler Airfoils

EPPLER 662 EPP662.DAT Raymer's book, ref NASA CP 2085
EPPLER 746
EPP746.DAT
Raymer's book, ref NASA CP 2085

Wortman Airfoils

FX-63-137-ESM
FX-72-MS-150A
FX-72-MS-150B
Miscellaneous Foils
ClarkY
Early Liebeck High Lift
NLR-1
RAE 100
RAE 101
RAE 102
RAE 103
RAE 104

FX63137.DAT
FX72M15A.DAT
FX72M15B.DAT

CLARKY.DAT
RHLHILFT.DAT
NLR1.DAT
Rotorcraft airfoil (NASA CP 2046, Vol. II)
RAE100.DAT
RAE101.DAT
RAE102.DAT
RAE103.DAT
RAE104.DAT

VariEze Airfoils
VariEze wing bl23 VEZBL32.DAT
VariEze winglet root VEZWLTR.DAT
VariEze winglet tip VEZWLTT.DAT
VariEze canard
Human powered aircraft airfoils
DAE 11 DAE11.DAT Daedalus airfoils (Mark Drela)
DAE 21
DAE 31
DAE 51
Lissaman 7769
DAE21.DAT
DAE31.DAT
DAE51.DAT (propeller foil?)
LISS769.DAT Gossamer Condor airfoil

Other airfoils are available on the world wide web, check App. F for sources. In particular, the Applied Aerodynamics group at the University of Illinois, under the direction of Prof. Michael Selig has established a massive online source for airfoil definitions and includes data from wind tunnel tests on the airfoils. Their focus is directed toward airfoils designed for low speeds and low Reynolds numbers. Finally, Richard Eppler has published an entire book of his airfoils, Airfoil design and data, Springer-Verlag, 1990.

The NASA low and medium speed airfoil program:

| NASA Low Speed, Medium Speed, and Natural Laminar Flow Airfoil Chart |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Airfoil Designation | Design Lift | Design Thickness | Design Mach | Test? | Ordinates in Airfoil Library? | Ref. | Comment |
| GA(W)-1 | .4/1.0 | . 17 |  | \% | 4 | TN D-7428 | Low Speed |
| LS(1)-0417mod |  | . 17 |  |  | 4 |  |  |
| GA(W)-2 |  | . 13 |  | 4 | 4 | TM X-72697 | " |
| mod |  | . 13 |  | 4 |  | TM X-74018 | " |
| ? |  | . 21 |  | 4 |  | TM 78650 | " |
| LS(1)-0013 |  | . 13 |  | 7 | 7 | TM-4003 | " |
| MS(1)-0313 |  | . 13 |  | $\checkmark$ | 4 | TP-1498 | Medium Speed |
| MS(1)-0317 | . 30 | . 17 | . 68 | $\checkmark$ | 4 | TP-1786 | " |
| mod |  | . 17 |  | $\checkmark$ |  | TP-1919 | " |
| NLF(1)-0215F | . 20 ? | . 15 | ? |  | 4 | Raymer's Book | Natural Laminar Flow |
| NLF(1)-0414F |  |  |  |  | 7 |  |  |
| NLF(1)-0416 |  |  |  |  | 4 |  |  |
| $\begin{aligned} & \text { NLF(1)-0414F } \\ & \text { drooped L.E. } \end{aligned}$ |  |  |  |  | 4 |  |  |
| NLF(2)-0415 | . 40 ? | . 15 ? | ? | 4 | 4 | Raymer's Book | " |
| $\operatorname{HSNLF}(1)-0213$ | . 20 ? | . 13 ? | ? |  | 4 | TM-87602 | " |
| $\begin{array}{\|c} \text { HSNLF(1)-0213 } \\ \bmod \end{array}$ |  |  |  |  | 4 |  |  |

The NASA Phase 2 supercritical airfoils are listed in the following chart.

| NASA Supercritical Airfoils - Phase $2^{\perp}$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Airfoil Designation | Design Lift | Design Thickness | Design <br> Mach | Test | Ordinates in Airfoil Library? | Ref. | Comment |
| $\mathrm{SC}(2)-0402$ | 0.40 | . 02 |  |  | 4 |  |  |
| SC(2)-0403 | 0.40 | . 03 |  |  | 4 |  |  |
| SC(2)-0503 | 0.50 | . 03 |  |  | 4 |  |  |
| SC(2)-0404 | 0.40 | . 04 |  |  | 7 |  |  |
| SC(2)-0406 | 0.40 | . 06 |  | 4 | 4 | unpubl. |  |
| SC(2)-0606 | 0.60 | . 06 |  |  | 4 |  |  |
| SC(2)-0706 | 0.70 | . 06 | . 795 | 4 | 4 | unpubl. |  |
| SC(2)-1006 | 1.00 | . 06 |  | 4 | 4 | unpubl. |  |
| SC(2)-0010 | 0.00 | . 10 |  |  | 4 |  |  |
| SC(2)-0410 | 0.40 | . 10 | . 785 |  | 4 |  |  |
| SC(2)-0610 | 0.60 | . 10 | . 765 |  | 4 |  |  |
| SC(2)-0710 | 0.70 | . 10 | . 755 | 4 | 4 | TM X-72711 | Airfoil 33 |
| SC(2)-1010 | 1.00 | . 10 | . 700 |  | 4 |  |  |
| SC(2)-0012 | 0.00 | . 12 |  | ? | 4 | TM-89102 |  |
| SC(2)-0412 | 0.40 | . 12 |  |  | $\checkmark$ |  |  |
| SC(2)-0612 | 0.60 | . 12 |  |  | 4 |  |  |
| SC(2)-0712 | 0.70 | . 12 | . 735 | ? | 4 | TM-86370 | TM-86371 |
| SC(2)-0414 | 0.40 | . 14 |  |  | 4 |  |  |
| SC(2)-0614 | 0.60 | . 14 |  |  | 4 |  |  |
| $\mathrm{SC}(2)-0714$ | 0.70 | . 14 | . 715 | 4 | $\psi_{\text {(Raymers) }}$ | TM X-72712 | Low Speed TM-81912 |
| SC(2)-0518 | 1.00 | . 18 |  |  | 4 |  |  |
| 1 Tabulated in NASA TP 2969, March 1990, by Charles D. Harris |  |  |  |  |  |  |  |

Several transonic airfoils were developed at New York University by a group led by Paul Garabedian. The following table provides a list of the airfoils they published.

| Garabedian and Korn Airfoil Chart |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Airfoil Designatio | Design Lift | Design Thickness | Design Mach | Test? | Ordinates in Airfoil Library? | Pages in Ref. Korn II Book | Comment |
| 79-03-12 | . 293 | . 123 | . 790 |  | 4 | 37,41-43 |  |
| 72-06-16 | . 609 | . 160 | . 720 |  | 4 | 48,52-54 |  |
| 71-08-14 | . 799 | . 144 | . 710 |  | 4 | 55,59-61 |  |
| 70-10-13 | . 998 | . 127 | . 700 |  | 4 | 62,66-68 |  |
| 65-14-08 | 1.409 | . 083 | . 650 |  | 7 | 73,77-79 |  |
| 65-15-10 | 1.472 | . 104 | . 650 |  | 4 | 80,84-86 |  |
| 82-06-09 | 0.590 | . 092 | . 820 |  | 4 | 91,95 |  |
| 75-06-12 | 0.629 | . 117 | . 750 | 4 | 4 | 96,99-101 | "The Korn" |
| 75-07-15 | 0.668 | . 151 | . 750 |  | 4 | 102,106 |  |

Their airfoils are included in:
Bauer, F., Garabedian, P., and Korn, D., A Theory of Supercritical Wing Sections with Computer Programs and Examples, Lecture Notes in Economics and Mathematical Systems, Vol. 66, Springer-Verlag, 1972.

Bauer, F., Garabedian, P., Jameson, A. and Korn, D., Supercritical Wing Sections II, A Handbook, Lecture Notes in Economics and Mathematical Systems, Vol. 108, SpringerVerlag, 1975.

Bauer, F., Garabedian, P., and Korn, D., Supercritical Wing Sections III, Lecture Notes in Economics and Mathematical Systems, Vol. 150, Springer-Verlag, 1977.

## A. 2 Classic Bodies of Revolution

Bodies of revolution form the basis for a number of shapes used in aerodynamic design and are also often used in comparing computational methods. The bodies defined in this section are generally associated with supersonic aerodynamics.

## a. Summary of Relations

The body radius $r$ is given as a function of $x, r / l=f(x / l)$. Once $r$ is known, a number of other values characterizing the shape can be determined.

The cross-sectional area and derivatives are:

$$
\begin{align*}
S(x) & =\pi r^{2}  \tag{A-39}\\
\frac{d S}{d x} & =2 \pi r \frac{d r}{d x}  \tag{A-40}\\
\frac{d^{2} S}{d x^{2}} & =2 \pi\left[\left(\frac{d r}{d x}\right)^{2}+r \frac{d^{2} r}{d x^{2}}\right] \tag{A-41}
\end{align*}
$$

Basic integrals are:
Volume,

$$
\begin{equation*}
V=\int_{0}^{l} S(x) d x \tag{A-42}
\end{equation*}
$$

Surface area,

$$
\begin{equation*}
S_{w e t}=2 \pi \int_{0}^{l} r(x) d x \tag{A-43}
\end{equation*}
$$

Length along the contour,

$$
\begin{equation*}
p(\bar{x})=\int_{0}^{l} \sqrt{1+\left(\frac{d r}{d x}\right)^{2}} d x \tag{A-44}
\end{equation*}
$$

Note that the incremental values can be found by changing the lower limit of the integrals. The local longitudinal radius of curvature is given by:

$$
\begin{equation*}
R(x)=\frac{\left[1+\left(\frac{d r}{d x}\right)^{2}\right]^{3 / 2}}{\left|\frac{d^{2} r}{d x^{2}}\right|} \tag{A-45}
\end{equation*}
$$

Several simple shapes are also of interest in addition to those presented in detail. They are:
Parabolic Spindle:

$$
\begin{equation*}
\frac{r}{l}=4 \frac{r_{\text {mid }}}{l} \frac{x}{l}\left(1-\frac{x}{l}\right) \tag{A-46}
\end{equation*}
$$

Ellipsoid of revolution:

$$
\begin{equation*}
\frac{r}{l}=2 \frac{r_{m i d}}{l} \sqrt{\frac{x}{l}\left(1-\frac{x}{l}\right)} \tag{A-47}
\end{equation*}
$$

and the power law body:

$$
\begin{equation*}
\frac{r}{l}=\frac{r_{0}}{l}\left(\frac{x}{x_{N}}\right)^{n} \tag{A-48}
\end{equation*}
$$

where $x_{N}$ is the nose length, and $r_{0}$ is the radius at $x=x_{N}$. The nose is blunt for $0<n<1$.
Another common shape is the spherical nose cap, and is discussed in detail in the reference by Krasnov. References that discuss geometry of bodies of revolution are:

Krasnov, N.F., Aerodynamics of Bodies of Revolution, edited and annotated by D.N. Morris, American Elsevier, New York, 1970.

Handbook of Supersonic Aerodynamics, Volume 3, Section 8, "Bodies of Revolution, NAVWEPS Report 1488, October 1961.

## b). Tangent/Secant Ogives

The tangent or secant ogives are frequently used shapes in supersonic aerodynamics. The nomenclature is illustrated in the following sketch.


Note that the ogive is actually the arc of a circle and when $\delta_{r}=0$ the ogive ends tangent to the body, so that $\delta_{r}=0$ represents the tangent ogive body. If $\delta_{r}=\delta_{N}$, the cone-cylinder is recovered. If $\delta_{r}=0$ and $\delta_{N}=90^{\circ}$, the spherical cap case is obtained.

The expression for the radius $r$ is determined using three basic constants for a particular case:

$$
\begin{align*}
& A=\frac{r_{0}}{l}\left(\frac{\cos \delta_{N}}{\cos \delta_{r}-\cos \delta_{N}}\right)  \tag{A-49}\\
& B=2 \frac{r_{0}}{l}\left(\frac{\sin \delta_{N}}{\cos \delta_{r}-\cos \delta_{N}}\right) \tag{A-50}
\end{align*}
$$

and

$$
\begin{equation*}
C=\frac{r_{0}}{l} \tag{A-51}
\end{equation*}
$$

The radius is then given by:

$$
\begin{array}{rlrl}
\frac{r}{l} & =\sqrt{A^{2}+B\left(\frac{x}{l}\right)-\left(\frac{x}{l}\right)^{2}}-A & 0 & <\frac{x}{l}<\frac{x_{N}}{l}  \tag{A-52}\\
& =C & \frac{x_{N}}{l}<\frac{x}{l}<1
\end{array}
$$

where $x_{N}$ is found as follows.
For a tangent ogive $\left(\delta_{r}=0\right)$, the ogive can be defined by specifying either $x_{N} / r_{0}$ or $\delta_{N}$. The other value can then be found using:

Given $\delta_{N}$,

$$
\begin{equation*}
\frac{x_{N}}{r_{0}}=\frac{\sin \delta_{N}}{1-\cos \delta_{N}} \tag{A-53}
\end{equation*}
$$

Or given $x_{N} / r_{0}$,

$$
\begin{equation*}
\delta_{N}=\cos ^{-1}\left[\frac{\left(\frac{x_{N}}{r_{0}}\right)^{2}-1}{\left(\frac{x_{N}}{r_{0}}\right)^{2}+1}\right] \tag{A-54}
\end{equation*}
$$

For the secant ogive, the simplest analytical procedure is to define the ogive in terms of $\delta_{N}$ and $\delta_{r}$, and then find $x_{N} / l$ from:

$$
\begin{equation*}
\frac{x_{N}}{l}=\frac{r_{0}}{l}\left(\frac{\sin \delta_{N}-\sin \delta_{r}}{\cos \delta_{r}-\cos \delta_{N}}\right) \tag{A-55}
\end{equation*}
$$

If $x_{N} / l$ is not satisfactory, $\delta_{N}$ and $\delta_{r}$ can be adjusted by trial and error to obtain the desired nose length. A program can be set up to handle this process quite simply.

The first and second derivatives are then given by:

$$
\begin{equation*}
\frac{d(r / l)}{d(x / l)}=\frac{B-2(x / l)}{2[(r / l)+A]} \tag{A-56}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d^{2}(r / l)}{d(x / l)^{2}}=-\frac{[B-2(x / l)]^{2}}{4[(r / l)+A]^{3}}-\frac{1}{[(r / l)+A]} \tag{A-57}
\end{equation*}
$$

The relationships between radius and area derivatives given in section $a$ ) are then used to complete the calculation.

## c) The von Kármán Ogive

The shape that produces minimum wave drag for a specified base area and length, according to slender body theory. This ogive has a very slightly blunted nose, and is described by Ashley and Landahl, Aerodynamics of Wings and Bodies, Addison-Wesley, 1965, pp. 178-181.

In this case it is convenient to work with the cross-sectional area and a new independent variable:

$$
\begin{equation*}
\theta=\cos ^{-1}\left[2\left(\frac{x}{x_{N}}\right)-1\right] \tag{A-58}
\end{equation*}
$$

or

$$
\begin{equation*}
\frac{x}{x_{N}}=\frac{1}{2}(1+\cos \theta) \tag{A-59}
\end{equation*}
$$

where the nose is at $\theta=\pi$, and the base is located at $\theta=0$.
Here we use $x_{N}$ to denote the "nose length" or length of the ogive, and allow this shape to be part of an ogive-cylinder geometry.

The shape is then given as:

$$
\begin{equation*}
\frac{S(x)}{l^{2}}=\frac{S_{B}}{l^{2}}\left[1-\frac{\theta}{\pi}+\frac{\sin 2 \theta}{2 \pi}\right] \tag{A-60}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{r}{l}=\sqrt{\frac{S / l^{2}}{\pi}} \tag{A-61}
\end{equation*}
$$

where $S_{B}$ is the prescribed base area and $l$ is the total length.
Defining

$$
\begin{equation*}
\bar{S}=\frac{S}{l^{2}}, \quad \bar{x}=\frac{x}{l} \tag{A-62}
\end{equation*}
$$

We have

$$
\begin{align*}
& \frac{d \bar{S}}{d \theta}=-\frac{\bar{S}_{B}}{\pi}[1-\cos 2 \theta]  \tag{A-63}\\
& \frac{d^{2} \bar{S}}{d \theta^{2}}=-\frac{2}{\pi} \bar{S}_{B} \sin 2 \theta \tag{A-64}
\end{align*}
$$

and

$$
\begin{gather*}
\frac{d \bar{S}}{d \bar{x}}=\bar{S}^{\prime}=\frac{4}{\pi}\left(\frac{l}{x_{N}}\right) \bar{S}_{B} \sin \theta  \tag{A-65}\\
\frac{d^{2} \bar{S}}{d \bar{x}^{2}}=\bar{S}^{\prime \prime}=-\frac{8}{\pi}\left(\frac{l}{x_{N}}\right)^{2} \frac{\bar{S}_{B}}{\tan \theta}
\end{gather*}
$$

The radius derivatives are then computed by:

$$
\begin{equation*}
\frac{d \bar{r}}{d \bar{x}}=\frac{\bar{S}^{\prime}}{2 \pi \bar{r}}, \quad \frac{d^{2} \bar{r}}{d \bar{x}^{2}}=\frac{\bar{S}^{\prime \prime}}{2 \pi \bar{r}}-\frac{\bar{r}^{\prime 2}}{\bar{r}} \tag{A-66}
\end{equation*}
$$

## d) The Sears-Haack Body

This is the minimum wave drag shape for a given length and volume according to slender body theory. The body is closed at both ends and has a very slightly blunted nose, and is symmetric about the mid-point. It is described by Ashley and Landahl, Aerodynamics of Wings and Bodies, Addison-Wesley, 1965, pp. 178-181.

Although the notation used in section $c$ ) for the von Kármán Ogive section could be used, it is more common to describe the Sears-Haack body in the manner presented below. This form uses the fineness ratio, $f=l / d_{\max }$ to scale the shape. However, it is important to realize that the Sears-Haack shape is the minimum drag body for a specified volume and length, not for a specified fineness ratio. The minimum drag body for a specified fineness ratio is described below in section $e$ ) below.

Defining

$$
\begin{equation*}
\varsigma=1-2\left(\frac{x}{l}\right), \tag{A-67}
\end{equation*}
$$

the Sears-Haack body is defined as

$$
\begin{equation*}
\frac{r}{l}=\frac{1}{2 f}\left(1-\varsigma^{2}\right)^{3 / 4} \tag{A-68}
\end{equation*}
$$

The derivatives are given by:

$$
\begin{equation*}
\frac{d(r / l)}{d(x / l)}=\frac{3 \varsigma}{1-\varsigma^{2}}\left(\frac{r}{l}\right) \tag{A-69}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d^{2}(r / l)}{d(x / l)^{2}}=-\left(\frac{1}{1-\varsigma^{2}}\right)\left[\varsigma \frac{d(r / l)}{d(x / l)}+6\left(\frac{r}{l}\right)\right] . \tag{A-70}
\end{equation*}
$$

The fineness ratio is related to the length and volume by:

$$
\begin{equation*}
f=\sqrt{\frac{3 \pi^{2}}{64} \frac{l^{3}}{V}} \tag{A-71}
\end{equation*}
$$

In terms of $f$ and either $V$ or $l$, the other value can be found from the following:
Given $f$ and $l$ :

$$
\begin{equation*}
V=\frac{3 \pi^{2}}{64} \frac{l^{3}}{f^{2}} \tag{A-72}
\end{equation*}
$$

Given $f$ and $V$ :

$$
\begin{equation*}
l=\left[V \frac{64}{3 \pi^{2}} f^{2}\right]^{1 / 3} . \tag{A-73}
\end{equation*}
$$

The relationships between radius and area derivatives given in Section a) are then used to complete the calculation.
e) The Haack-Adams Bodies

The Haack-Adams bodies define a number of minimum drag shapes, as described by M.C. Adams in "Determination of Shapes of Boattail Bodies of Revolution for Minimum Wave Drag," NACA TN 2550, November 1951. These bodies correspond to the following cases:
I. Given length, base area, and contour passing through a specifically located radius.
II. Given length, base area, and maximum area.
III. Given length, base area, and volume.

In case I, the specified radius will not necessarily be the maximum radius.
The notation used in TN 2550 is employed in the equations, leading to the following definitions:

$$
\begin{equation*}
S=4 \frac{\bar{S}(x)}{l^{2}}, \quad B=4 \frac{S_{B A S E}}{l^{2}}, \quad A=4 \frac{S_{A}}{l^{2}}, \quad V=8\left(\frac{\bar{V}}{l^{3}}\right) \tag{A-74}
\end{equation*}
$$

where $S(x)$ is the area, $S_{A}$ corresponds to either the specified area at a given location, or the maximum area, and $V$ is the volume. The independent variable is defined with its origin at the body mid-point:

$$
\begin{equation*}
\varsigma=2\left(\frac{x}{l}\right)-1 \tag{A-75}
\end{equation*}
$$

and the location of the specified radius (Case I) and maximum radius (Case II) is designated C and given in $\zeta$ coordinates. When referred to the $x$ coordinate, this value is designated $C_{x}$.

The equation for each case can be written in a standard form:
Case I — Given $S_{B A S E}, S_{A}, C_{X}$ :

$$
\begin{align*}
\frac{\pi S}{B}= & {\left[\frac{\pi A}{B}-\cos ^{-1}(-c)\right] \frac{\sqrt{1-\varsigma^{2}}(1-c \varsigma)}{\left(1-c^{2}\right)^{3 / 2}}+\frac{\sqrt{1-\varsigma^{2}}(\varsigma-c)}{\left(1-c^{2}\right)} }  \tag{A-76}\\
& +\left[\frac{\pi A}{B}-\cos ^{-1}(c)-c \sqrt{1-c^{2}}\right] \frac{(\varsigma-c)^{2}}{(1-c)^{2}} \ln N+\cos ^{-1}(-\varsigma)
\end{align*}
$$

where

$$
\begin{equation*}
N=\frac{1-c \varsigma-\sqrt{1-c^{2}} \sqrt{1-\varsigma^{2}}}{|\varsigma-c|} . \tag{A-77}
\end{equation*}
$$

Case II - Given $S_{B A S E}, S_{M A X}$ :
First find the location of the maximum thickness from the implicit relation

$$
\begin{equation*}
f(c)=0=\frac{\pi A}{B} c-\sqrt{1-c^{2}}-c \cos ^{-1}(-c) . \tag{A-78}
\end{equation*}
$$

Use Newton's iteration

$$
\begin{equation*}
c^{i+1}=c^{i}-\frac{f\left(c^{i}\right)}{f^{\prime}\left(c^{i}\right)} \tag{A-79}
\end{equation*}
$$

where

$$
\begin{equation*}
f^{\prime}(c)=\frac{\pi A}{B}-\cos ^{-1}(-c) \tag{A-80}
\end{equation*}
$$

An initial guess of $c=0$ is sufficient to start the iteration. Given $c$, the relation for the area is:

$$
\begin{equation*}
\frac{\pi S}{B}=\frac{\sqrt{1-\varsigma^{2}}}{c}+\frac{(\varsigma-c)^{2}}{c \sqrt{1-c^{2}}} \ln N+\cos ^{-1}(-\varsigma) \tag{A-81}
\end{equation*}
$$

where $N$ is the same function as given in Case I.
Case III - Given $S_{B A S E}$ and $V$ :

$$
\begin{equation*}
\frac{\pi S}{B}=\frac{8}{3}\left[\frac{V}{B}-1\right]\left(1-\varsigma^{2}\right)^{3 / 2}+\varsigma \sqrt{1-\varsigma^{2}}+\cos ^{-1}(-\varsigma) \tag{A-82}
\end{equation*}
$$

The maximum thickness for this case is located at:

$$
\begin{equation*}
e=\frac{1}{4(V / B-1)} \tag{A-83}
\end{equation*}
$$

and in $x$ coordinates

$$
\begin{equation*}
e_{x}=\frac{1}{2}(1+e) \tag{A-84}
\end{equation*}
$$

Note that if $S_{B A S E}=0$, the Sears-Haack body is recovered.

## A. 3 Cross-Section Geometries for Bodies

The axisymmetric bodies described above can be used to define longitudinal lines for aerodynamic bodies. However, many aerodynamic bodies are not axisymmetric (the fuselage cross section is not round). In this section we define a class of cross section shapes that can be used to develop more realistic aerodynamic models. In particular, they have been used to study geometric shaping effects on forebody aerodynamic characteristics using an analytical forebody model with the ability to produce a wide variation of shapes. This generic model makes use of the equation of a super-ellipse to define cross sectional geometry. The super-ellipse, used previously to control flow expansion around wing leading edges, can recover a circular cross section, produce elliptical cross sections and can also produce chine-shaped cross sections. Thus it can be used to define a variety of different cross sectional shapes.

The super-ellipse equation for a cross section is:

$$
\begin{equation*}
\left(\frac{z}{b}\right)^{2+n}+\left(\frac{y}{a}\right)^{2+m}=1 \tag{A-85}
\end{equation*}
$$

where $n$ and $m$ are adjustable coefficients that control the surface slopes at the top and bottom plane of symmetry and chine leading edge. The constants $a$ and $b$ correspond to the maximum half-breadth (the maximum width of the body) and the upper or lower centerlines respectively. Depending on the value of $n$ and $m$, the equation can be made to produce all the shapes described above. The case $n=m=0$ corresponds to the standard ellipse. The body is circular when $a=b$.

When $n=-1$ the sidewall is linear at the maximum half breadth line, forming a distinct crease line. When $n<-1$ the body cross section takes on a cusped or chine-like shape. As $n$ increases, the cross-section starts to become rectangular.

The derivative of $z / b$ with respect to $y / a$ is:

$$
\begin{equation*}
\frac{d \bar{z}}{d \bar{y}}=-\frac{\left(\frac{2+m}{2+n}\right)}{\left[1-\bar{y}^{(2+m)}\right]^{\left(\frac{1+n}{2+n}\right)}} \tag{A-86}
\end{equation*}
$$

where $\bar{z}=z / b$ and $\bar{y}=y / a$. As $\bar{y} \rightarrow 1$, the slope becomes:

$$
\frac{d \bar{z}}{d \bar{y}}= \begin{cases}\infty & n>-1  \tag{A-87}\\ 0 & n<-1 \\ -(2+m) \bar{y}^{1+m} & n=-1\end{cases}
$$

The following sketch shows a quadrant of the cross section for various values of $n$ ranging from a chine to a rectangle.


Different cross sections can be used above and below the maximum half-breadth line. Even more generality can be provided by allowing $n$ and $m$ to be functions of the axial distance $x$. The parameters $a$ and $b$ can also be functions of the planform shape and varied to study planform effects. Notice that when $n=-1$ the value of $m$ can be used to control the slope of the sidewall at the crease line. Also, observe that large positive values of $n$ drives the cross section shape to approach a rectangular or square shape.

Connecting various cross section shapes is part of the subject of lofting, described here in Chapter 9. One of the few other textbook discussions is contained in Raymer, Aircraft Design: A Conceptual Approach, published by the AIAA, in Chapter 7. Dan Raymer worked at North American Aviationn, where Liming literally wrote the book on the analytic definition of aircraft lines.

## A. 4 Planform Analysis

Several local and integral planform properties are of interest in aerodynamic analysis. They are summarized in this section. (Note: Biplanes use the total area of both wings as the reference area). For a more complete presentation see DATCOM.

The local values are the leading and trailing edge locations, $x_{\mathrm{LE}}(y)$ and $x_{\mathrm{TE}}(y)$, the local chord, $c(y)$, and the leading and trailing edge sweep angles: $\Lambda_{\mathrm{LE}}(y)$ and $\Lambda_{\mathrm{TE}}(y)$. The following sketch illustrates the standard nomenclature.


The integral properties are (assuming the planform is symmetric):

1. Planform Area, $S$

$$
\begin{equation*}
S=2 \int_{0}^{b / 2} c(y) d y \tag{A-88}
\end{equation*}
$$

2. Mean aerodynamic chord, mac

$$
\begin{equation*}
\bar{c}=\frac{2}{S} \int_{0}^{b / 2} c^{2}(y) d y \tag{A-89}
\end{equation*}
$$

3. X position of centroid of area, $x_{\text {cen }}$

$$
\begin{equation*}
x_{\text {cen }}=\frac{2}{S} \int_{0}^{b / 2} c(y)\left\{x_{L E}(y)+\frac{c(y)}{2}\right\} d y \tag{A-90}
\end{equation*}
$$

4. Spanwise position of mac

$$
\begin{equation*}
y_{m a c}=\frac{2}{S} \int_{0}^{b / 2} y c(y) d y \tag{A-91}
\end{equation*}
$$

5. Leading edge location of mac.

$$
\begin{equation*}
x_{L E_{\text {mac }}}=\frac{2}{S} \int_{0}^{b / 2} x_{L E}(y) c(y) d y \tag{A-92}
\end{equation*}
$$

In addition, the following derived quantities are often of interest:
Aspect Ratio:

$$
\begin{equation*}
A R=\frac{b^{2}}{S_{r e f}} \tag{A-93}
\end{equation*}
$$

Average Chord:

$$
\begin{equation*}
c_{A}=\frac{S_{r e f}}{b} \tag{A-94}
\end{equation*}
$$

Taper Ratio:

$$
\begin{equation*}
\lambda=\frac{c_{T}}{c_{R}} \tag{A-95}
\end{equation*}
$$

$S_{r e f}$ is usually chosen to be equal to the area of a basic reference trapezoidal planform, and thus the actual planform area, $S$, may not equal $S_{r e f}$.

When considering two areas, recall that the centroid of the combined surfaces is:

$$
\begin{align*}
& S \bar{x}=S_{1} \bar{x}_{1}+S_{2} \bar{x}_{2}  \tag{A-96}\\
& S \bar{y}=S_{1} \bar{y}_{1}+S_{2} \bar{y}_{2} .
\end{align*}
$$

For a standard trapezoidal wing it is convenient to collect the following formulas, where the sketch shows the nomenclature:


$$
\begin{align*}
& x_{L E}(y)=x_{L E_{0}}+y \tan \Lambda_{L E}(y)  \tag{A-97}\\
& x_{T E}(y)=x_{T E_{0}}+y \tan \Lambda_{T E}(y)
\end{align*}
$$

and the local chord is:

$$
\begin{equation*}
\frac{c(y)}{c_{R}}=1-(1-\lambda) \eta \tag{A-98}
\end{equation*}
$$

where:

$$
\begin{equation*}
y=\frac{b}{2} \eta \quad \text { or } \quad \eta=\frac{y}{b / 2} \quad \text { and } \quad \lambda=\frac{c_{T}}{c_{R}} . \tag{A-99}
\end{equation*}
$$

The sweep at any element line can be found in terms of the sweep at any other by:

$$
\begin{equation*}
\tan \Lambda_{n}=\tan \Lambda_{m}-\frac{4}{A R}\left[(n-m)\left(\frac{1-\lambda}{1+\lambda}\right)\right] \tag{A-100}
\end{equation*}
$$

where $n, m$ are fractions of the local chord. An alternate formula is available using the trailing edge sweep angle:

$$
\begin{equation*}
\tan \Lambda_{n}=(1-n) \tan \Lambda_{L E}+n \tan \Lambda_{T E} \tag{A-101}
\end{equation*}
$$

The integral and other relations are given by:

$$
\begin{align*}
S & =\frac{b}{2} c_{R}(1+\lambda) \\
c_{\text {ave }} & =\frac{S}{b} \\
\frac{\bar{c}}{c_{R}} & =\frac{2}{3}\left(\frac{1+\lambda+\lambda^{2}}{1+\lambda}\right) \\
A R=\frac{b^{2}}{S} & =\frac{b / 2}{c_{R}}\left(\frac{4}{1+\lambda}\right) \\
y_{\text {mac }} & =\frac{b}{6}\left(\frac{1+2 \lambda}{1+\lambda}\right) \\
\frac{x_{L E_{m a c}}}{c_{R}} & =\frac{x_{L E_{0}}}{c_{R}}+\left(\frac{1+2 \lambda}{12}\right) A R \tan \Lambda_{L E} \\
x_{\text {cen }} & =x_{L E_{m a c}}+\frac{\bar{c}}{2}  \tag{A-102}\\
A R & =\frac{b^{2}}{S}=\frac{b / 2}{c_{R}}\left(\frac{4}{1+\lambda}\right)
\end{align*}
$$

When computing the projected planform area of an entire configuration, the following formula is useful:

$$
\begin{equation*}
S=\sum_{k=1}^{k=N}\left(y_{k+1}+y_{k}\right)\left(x_{k+1}-x_{k}\right) \tag{A-103}
\end{equation*}
$$

where the sketch below defines the nomenclature.
At $k=\mathbf{N}, y_{k+1}, x_{k+1}$ refer to the initial points $y_{1}, x_{1}$. For normal planforms, $y_{n+1}=y_{1}=0$, so that the summation can be terminated at $\mathrm{N}-1$. This formula assumes planform symmetry and provides the total planform area with only one side of the planform used in the computation.


## A. 5 Conical Camber

An important class of camber distributions is associated with the planform, and not the airfoil. Conical camber has been widely used. Many forms have been used, however the NACA defined a specific type of conical camber that is known as NACA conical camber. The most recent example of NACA conical camber is the F-15 wing. It improves the drag characteristics of wings in the subsonic and transonic flow region even though it was developed to reduce the drag at supersonic speeds!

The key references are:
Hall, C.F., "Lift, Drag, and Pitching Moment of Low Aspect Ratio Wings at Subsonic and Supersonic Speeds," NACA RM A53A30, 1953.

This report provided the original mathematical definition of NACA conical camber. It also provided a large range of test conditions for which the camber was effective.

Boyd, J.W., Migotsky,E., and Wetzel, B.E., "A Study of Conical Camber for Triangular and Swept Back Wings," NASA RM A55G19, Nov. 1955.

This report provided more details of the derivation of the formulas for NACA conical camber, and corrected errors in the equations presented in the first report. Additional experimental results were also presented.

## A. 6 Three-Dimensional Wing Geometry

Wing geometry is often defined by interpolating between airfoil section-specified at particular spanwise stations. Some care some be taken to interpolate properly. See Chapter 9, Geometry and Grids for a discussion of wing lofting. Program WNGLFT is described in App. E, Utility Codes. This program provides an example of a lofting scheme to provide wing ordinates at any desired location. It can be used to provide wing ordinates for a wide class of wings. It in fact will produce a very good approximation to the wing design employed by a successful Navy airplane.


[^0]:    * Additional section data is contained in NASA R-84, 1958, by Patterson and Braslow.

[^1]:    * Only the mean lines have analytical definitions. The thickness distributions are the result of numerical methods which produced tabulated coordinates. In addition to the values tabulated in the NACA reports, the closest approximation for the thickness distributions is available in program LADSON, see App. E.

